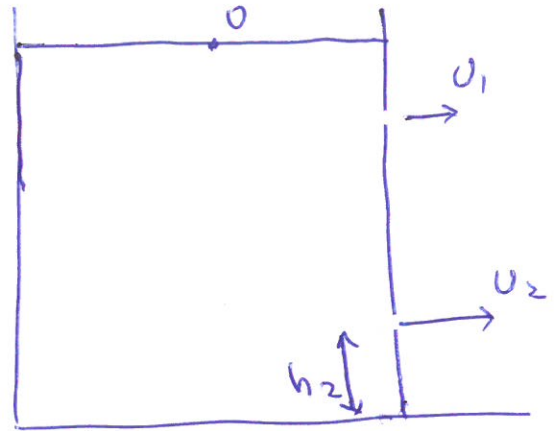


$$B_2) A_1 = A_2 = A$$

$$h_1 = \frac{5H}{6}$$

$$h_2 = \frac{H}{3}$$



Bernoulli 0 → 1

$$v_1 = \sqrt{2g(H-h_1)} \Rightarrow v_1 = \sqrt{2g \frac{H}{6}} \Rightarrow v_1 = \sqrt{\frac{gH}{3}} \quad (1)$$

Bernoulli 0 → 2

$$v_2 = \sqrt{2g(H-h_2)} = \sqrt{2g\left(H - \frac{H}{3}\right)} \Rightarrow v_2 = \sqrt{\frac{4gH}{3}} \quad (2)$$

$$(1) \text{ \& } (2) \quad \frac{v_1}{v_2} = \frac{\sqrt{\frac{gH}{3}}}{\sqrt{\frac{4gH}{3}}} = \frac{1}{2} \Rightarrow \boxed{v_2 = 2v_1} \Rightarrow$$

$$\Rightarrow A \cdot v_2 = 2A v_1 \Rightarrow \Pi_2 = 2\Pi_1 \quad (3)$$

Αρχικά $\Pi_{02} = \Pi_1 = \frac{V}{\Delta t_1} \Rightarrow \Delta t_1 = \frac{V}{\Pi_1} \quad (4)$

Τελικά $\Pi'_{02} = \Pi_1 + \Pi_2 \stackrel{(3)}{\Rightarrow} \Pi'_{02} = 3\Pi_1 = \frac{V}{\Delta t_2} \Rightarrow$

$$\Rightarrow \Delta t_2 = \frac{V}{3\Pi_1} \quad (5) \quad \frac{(4)}{(5)} \quad \frac{\Delta t_2}{\Delta t_1} = \frac{\frac{V}{3\Pi_1}}{\frac{V}{\Pi_1}} \Rightarrow \boxed{\frac{\Delta t_2}{\Delta t_1} = \frac{1}{3}}$$

Σωστό το (ii)

-2-

$$B_3) \quad \left. \begin{aligned} P_1 &= m v_1 \\ P_1' &= \frac{P_1}{S} = \frac{m v_1'}{S} \end{aligned} \right\} \text{Αρα } v_1' = \frac{v_1}{S} \Rightarrow$$

$$\Rightarrow \frac{m_1 - m_2}{m_1 + m_2} v_1 = \frac{v_1'}{S} \Rightarrow S m_1 - S m_2 = m_1 + m_2 \Rightarrow$$

$$4 m_1 = 6 m_2 \Rightarrow m_1 = \frac{3}{2} m_2 \quad (2)$$

$$v_2' = \frac{2 m_1}{m_1 + m_2} v_1 = \frac{2 \cdot \frac{3}{2} m_2}{\frac{3}{2} m_2 + m_2} v_1 = \frac{3 m_2}{\frac{5}{2} m_2} v_1 = \frac{6}{5} v_1 \Rightarrow$$

$$\Rightarrow v_2' = \frac{6}{5} v_1$$

$$\Pi = \frac{\Delta K_2}{K_1} \cdot 100\% = \frac{K_2' - K_2}{K_1} \cdot 100\% \Rightarrow$$

$$\Pi = \frac{\frac{1}{2} m_2 v_2'^2}{\frac{1}{2} m_1 v_1^2} \cdot 100\% = \frac{m_2 \cdot \frac{36}{25} v_1^2}{\frac{3}{2} m_2 v_1^2} \cdot 100\% = \frac{2 \cdot 36}{3 \cdot 25} \cdot 100\%$$

$$\boxed{\Pi = 96\%}$$

Σωστό το (iii)

ΘΕΜΑ Γ

$$l = 1\text{m}$$

$$E = 9\text{V}$$

$$r = 1\Omega$$

$$m = 0,3\text{kg}$$

$$R_{\text{ext}} = 2\Omega$$

$$\Gamma_1) B = ?$$

$$R_1 = 3\Omega$$

$$V_k = 6\text{V}$$

$$P_k = 6\text{W}$$

$$\Gamma_2) V_{\text{op}} = ?$$

$$\Gamma_3) \frac{dP}{d\varepsilon} = ?$$

$$0 = \frac{dP}{d\varepsilon}$$

$\Gamma_1)$ Για να

ισορροπεί ο αγωγός

θα πρέπει να

$\vec{F}_{\text{ext}}$ να έχει

φορά προς τα πάνω. Από $\vec{B} \otimes$

$$\Sigma F = 0 \Rightarrow F_{\text{ext}} = w \Rightarrow BIl = mg \Rightarrow$$

$$B \frac{E}{R_0} l = mg \Rightarrow B = \frac{mg(R + R_{\text{ext}})}{E \cdot l}$$

$$\Rightarrow B = \frac{3 \cdot (1+2)}{9 \cdot 1} = \boxed{B = 1\text{T}}$$

$$\Gamma_2) P_k = V_k I_k \Rightarrow \boxed{I_k = 1\text{A}}$$

$$I_k = \frac{V_k}{R_{\text{ext}}} \Rightarrow \boxed{R_{\text{ext}} = 6\Omega}$$

• Ισορροπία

$$R_{\text{ext}} = \frac{R_1 \cdot R_{\text{ext}}}{R_1 + R_{\text{ext}}} \Rightarrow R_{\text{ext}} = 2\Omega$$

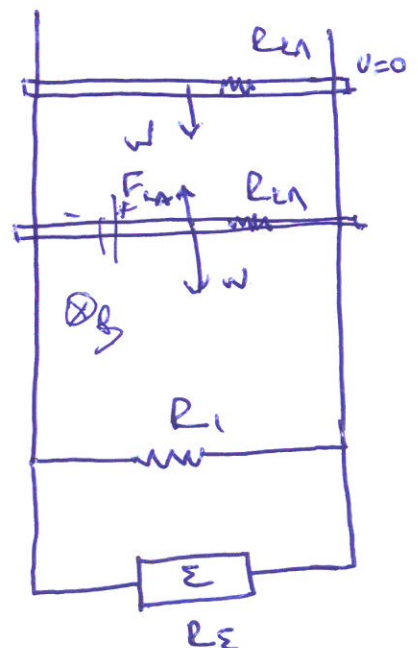
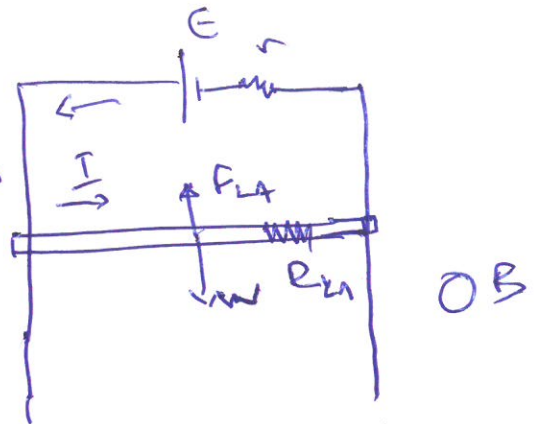
$$R_{\text{ext}} = R_{\text{ext}} + R_{\text{ext}} \Rightarrow$$

$$\boxed{R_{\text{ext}} = 4\Omega}$$

Ισορροπία
δυνάμεις

$$\Sigma F = ma \Rightarrow w - F_{\text{ext}} = ma$$

$$mg = BIl = ma \Rightarrow$$



$$\Rightarrow mg - B \cdot \frac{\mathcal{E}_{en}}{R_{ext}} l = ma \Rightarrow mg - B \cdot \frac{B_0 l}{R_{ext}} l = ma$$

$$\Rightarrow 3 - \frac{0}{4} = 0,3a \Rightarrow a = 10 - \frac{0}{1,2} \Rightarrow a = 10 - \frac{50}{6} \text{ (Σ)} \quad (1)$$

Από τη σχέση (1) φαίνεται ότι όσο η ταχύτητα αυξάνεται, η επιτάχυνση μειώνεται.

Αρα το σώμα θα έχει επιταχυνόμενη κίνηση με μειούμενη επιτάχυνση.

$$\text{Όταν } \Sigma F = 0 \Rightarrow a = 0 \Rightarrow 10 - \frac{50}{6} = 0 \Rightarrow$$

$$\Rightarrow \boxed{v_{op} = 12 \text{ m/s}}$$

$$\Gamma_3) \quad v = \frac{v_{op}}{2} \Rightarrow v = 6 \text{ m/s}$$

$$|| \quad a = 10 - \frac{5 \cdot 6}{6} \Rightarrow a = 5 \text{ m/s}^2$$

$$\frac{dp}{dt} = \Sigma F = ma = 0,3 \cdot 5 \Rightarrow \boxed{\frac{dp}{dt} = 1,5 \text{ kg m/s}^2}$$

$$\Gamma_4) \quad \text{Για } v_{op} \text{ ισχύει } I_{en} = \frac{\mathcal{E}_{en}}{R_{ext}} = \frac{B v_{op} l}{R_{ext}} \Rightarrow I_{en} = 3 \text{ A}$$

$$V_e = V_{\eta} \Rightarrow V_{\eta} = \mathcal{E}_{en} - I_{en} R_{int} \Rightarrow V_{\eta} = B v_{op} l - I_{en} R_{int}$$

$$\Rightarrow \boxed{V_{\eta} = 6 \text{ V}}$$

$$\text{Όπως } V_{\eta} = V_{\Sigma} = V_e$$

άρα λειτουργεί
κατάλληλα

ΘΕΜΑ Δ

$$M_p = 3 \text{ kg}$$

$$l = 2 \text{ m}$$

$$m = 1 \text{ kg}$$

$$\eta \mu \phi = 0,8$$

$$\beta \omega \phi = 0,6$$

$$M_T = 7 \text{ kg}$$

$$R = 0,4 \text{ m}$$

$$r = 0,3 \text{ m}$$

$$\Delta_1) T_1 = 10,5 \text{ N}$$

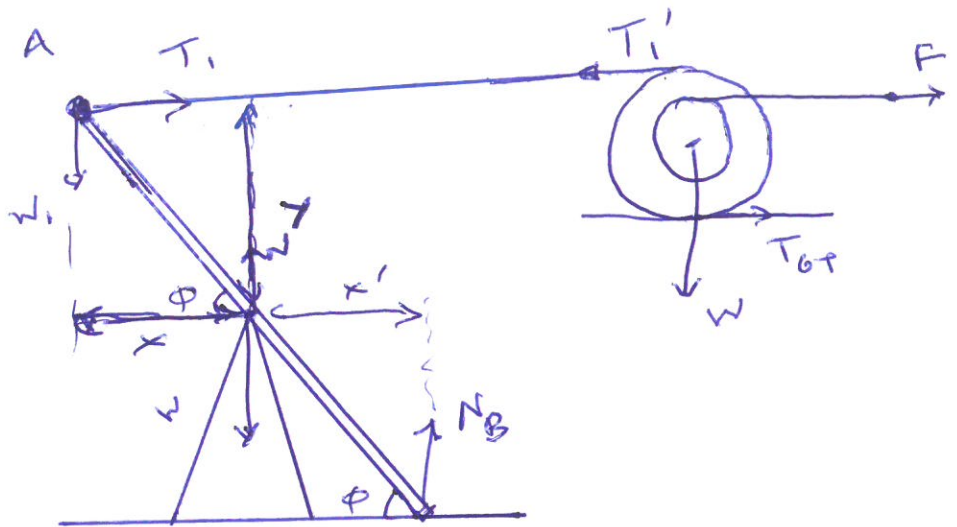
$$N_B = ?$$

$$\Delta_2) \left(\frac{dL}{dt} \right)_{\text{πύλ}} = ?$$

$$\Delta_3) (\Delta L) = ?$$

$$\Delta_4) F = 12 \text{ N}$$

$$a_{\text{cm}} = ?$$



Η ράβδος ισορροπεί

$$\Delta_1) \sum \tau(r) = 0 \Rightarrow \tau_{w_1} + \tau_{T_1} + \tau_{N_B} = 0$$

$$\Rightarrow w_1 \cdot x - T_1 \cdot y + N_B \cdot x' = 0 \quad (1)$$

$$\eta \mu \phi = \frac{y}{\frac{l}{2}} \Rightarrow y = \frac{l}{2} \cdot \eta \mu \phi$$

$$\beta \omega \phi = \frac{x}{\frac{l}{2}} \Rightarrow x = \frac{l}{2} \beta \omega \phi$$

$$\beta \omega \phi = \frac{x'}{\frac{l}{2}} \Rightarrow x' = \frac{l}{2} \beta \omega \phi$$

$$(1) w_1 \cdot \frac{l}{2} \beta \omega \phi - T_1 \cdot \frac{l}{2} \eta \mu \phi + N_B \cdot \frac{l}{2} \beta \omega \phi = 0$$

$$N_B \cdot 0,6 = 10,5 \cdot 0,8 - 10 \cdot 0,6 \Rightarrow$$

$$6 N_B = 8 \cdot 10,5 - 6 \cdot 10 \Rightarrow \boxed{N_B = 4 \text{ N}}$$

Δ2) Για το σώμα
 $\sum \tau = I_{O_2} \cdot \alpha_{\text{γων}} \Rightarrow$

$$\Rightarrow W_1 \cdot x = (I_p + I_1) \alpha_{\text{γων}} \Rightarrow$$

$$\Rightarrow \alpha_{\text{γων}} = \frac{m_1 g \frac{l}{2} \cdot 0,6 \omega \phi}{\frac{1}{12} M l^2 + m_1 \left(\frac{l}{2}\right)^2} \Rightarrow$$

$$\Rightarrow \alpha_{\text{γων}} = \frac{m_1 g \frac{l}{2} \cdot 0,6 \omega \phi}{\frac{1}{12} M l^2 + m_1 \frac{l^2}{4}} = \frac{1 \cdot 10 \cdot \frac{1}{2} \cdot 0,6}{\frac{1}{12} \cdot 3 \cdot 2 + \frac{1}{2}} \Rightarrow \boxed{\alpha_{\text{γων}} = 3 \text{ rad/s}^2}$$

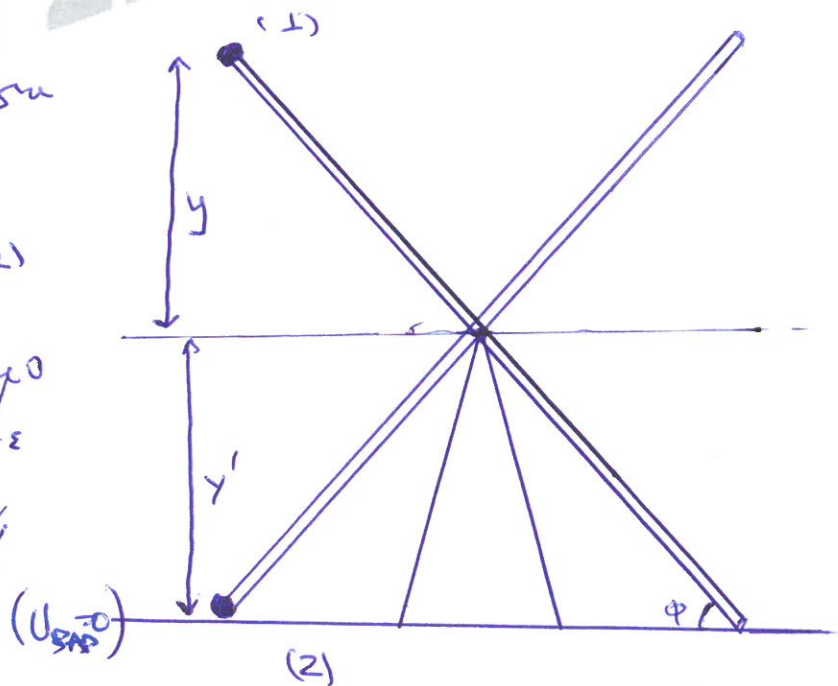
Αρα για το πύλο $\left(\frac{dL}{dt}\right)_{\text{παθ}} = I_p \cdot \alpha_{\text{γων}} = \frac{1}{12} M l^2 \alpha_{\text{γων}}$

$$\Rightarrow \left(\frac{dL}{dt}\right)_{\text{παθ}} = \frac{1}{12} \cdot 3 \cdot 2^2 \cdot 3 \Rightarrow \boxed{\left(\frac{dL}{dt}\right)_{\text{παθ}} = 3 \text{ kg m}^2/\text{s}^2}$$

Δ3) Εφαρμόζω ΑΔΜΕ για το σώμα από τη θέση (1) bzw θέση (2)

$$\cancel{K_1 + U_{1p} + U_{1\varepsilon} = K_2 + U_{2p} + U_{2\varepsilon}}$$

$$\cancel{M g y' + m g (y' + y) = \frac{1}{2} I_{O_2} \omega^2 + M g y'}$$



$$m g (y' + y) = \frac{1}{2} \left(\frac{1}{12} M l^2 + m \frac{l^2}{4} \right) \omega^2 \Rightarrow$$

$$\eta \phi = \frac{y'}{l/2}$$

$$y' = \frac{l}{2} \eta \phi$$

$$m g \left(\frac{l}{2} \eta \phi + \frac{l}{2} \eta \phi \right) = \frac{1}{2} \left(\frac{1}{12} M l^2 + m \frac{l^2}{4} \right) \omega^2$$

-7-

$$\Rightarrow 10 \cdot 0,8 = \frac{1}{2} \left(\frac{1}{2} + \frac{2}{4} \right) \omega^2 \Rightarrow \boxed{\omega = 4 \text{ rad/s}}$$

$$L_{APX} \text{ } \odot$$

$$\Delta L = L' - L \Rightarrow \Delta L =$$

$$L_{TEA} \text{ } \otimes$$

$$\Delta L = I \cdot \omega' - (-I\omega) \Rightarrow$$

$$\otimes (H)$$

$$\Delta L = I \cdot \frac{\omega}{2} + I\omega \Rightarrow \Delta L = \frac{3}{2} \cdot I \cdot \omega \Rightarrow$$

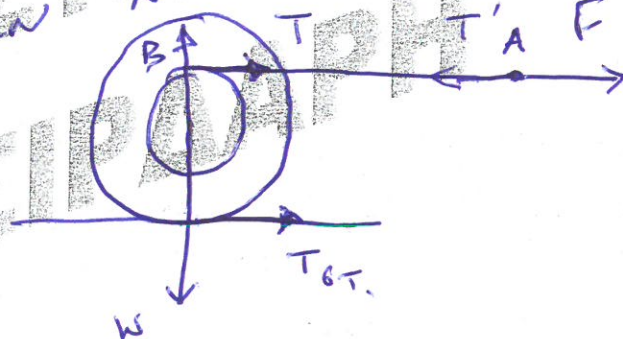
$$\Delta L = \frac{3}{2} \cdot \left(\frac{1}{12} M L^2 + m \frac{L^2}{4} \right) \cdot \omega \Rightarrow \boxed{|\Delta L| = 12 \text{ kg m}^2/\text{s}}$$

$$M \text{ } \phi \text{ } \rho \text{ } \rho \text{ } \Delta L^+ \text{ } \otimes$$

$$\Delta 4) \left. \begin{array}{l} I_{\omega \omega \Sigma} \\ F = T' \\ T = T' \end{array} \right\} F = T = 12 \text{ N}$$

$$\Sigma F_x = M \cdot a_{\text{cm}} \Rightarrow$$

$$T + T_{\text{GT}} = M a_{\text{cm}} \quad (2)$$



$$\Sigma \tau = I \alpha_{\omega} \Rightarrow T r - T_{\text{GT}} R = \frac{1}{2} M R^2 \cdot \frac{a_{\text{cm}}}{R} \quad (\text{ex } 0)$$

$$\Rightarrow T \cdot \frac{3R}{4} - T_{\text{GT}} R = \frac{1}{2} M R a_{\text{cm}} \Rightarrow \frac{3T}{4} - T_{\text{GT}} = \frac{1}{2} M a_{\text{cm}} \quad (3)$$

$$(2) + (3) \quad T + \frac{3T}{4} = \frac{1}{2} M a_{\text{cm}} + M a_{\text{cm}} \Rightarrow \frac{7T}{4} = \frac{3}{2} M a_{\text{cm}} \Rightarrow$$

$$\Rightarrow \frac{7 \cdot 12}{4} = \frac{3}{2} \cdot 7 a_{\text{cm}} \Rightarrow \boxed{a_{\text{cm}} = 2 \text{ m/s}^2}$$

$$\Delta 5) \quad I_{B \times O_2} \quad v_A = v_B \Rightarrow v_A = v_{cm} + v_{sp} \Rightarrow$$

$$v_A = \omega R + \omega r \Rightarrow v_A = \omega R + \omega \frac{3R}{4} \Rightarrow$$

$$v_A = \frac{7}{4} \omega R \Rightarrow v_A = \frac{7}{4} v_{cm} \Rightarrow \frac{dv_A}{dt} = \frac{7}{4} \frac{dv_{cm}}{dt}$$

$$\Rightarrow a_A = \frac{7}{4} a_{cm} \quad (4)$$

$$W_F = F \cdot x_4 = F \cdot \frac{1}{2} a_A \cdot t^2$$

$$W_F = F \cdot \frac{1}{2} \cdot \frac{7}{4} a_{cm} t^2 \Rightarrow W_F = 12 \cdot \frac{1}{2} \cdot \frac{7}{4} \cdot 2 \cdot 2^2$$

$$W_F = 84 \text{ J}$$

Καλὰ

Αποτέλεσμα